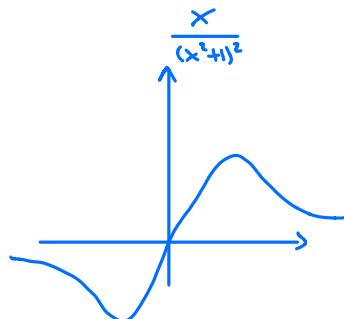


More on improper integrals ...

Definition:

$\int_{-\infty}^{\infty} f(x) dx := \int_{-\infty}^0 f(x) dx + \int_0^{\infty} f(x) dx$, if both integrals exist, is also called improper integral.

$$\begin{aligned} \text{Ex.: } \int_{-\infty}^{\infty} \frac{x}{(x^2+1)^2} dx &= \int_{-\infty}^0 \frac{x}{(x^2+1)^2} dx + \int_0^{\infty} \frac{x}{(x^2+1)^2} dx \\ &= -\frac{1}{2} \left. \frac{1}{x^2+1} \right|_{-\infty}^0 - \frac{1}{2} \left. \frac{1}{x^2+1} \right|_0^{\infty} \\ &= -\frac{1}{2} - 0 + (0 - (-\frac{1}{2})) \\ &= 0 \end{aligned}$$



$$\int_{-\infty}^{\infty} x dx = \int_{-\infty}^0 x dx + \int_0^{\infty} x dx \quad \text{does not exist!}$$

$$(\text{note: } \int_{-\infty}^{\infty} x dx \neq \lim_{b \rightarrow \infty} \int_{-b}^b x dx = \lim_{b \rightarrow \infty} \frac{x^2}{2} \Big|_{-b}^b = 0)$$

Definition:

If $f: (a, b] \rightarrow \mathbb{R}$ is singular at $a \in \mathbb{R}$ (i.e., $\lim_{\varepsilon \rightarrow 0} f(a \pm \varepsilon) = \pm \infty$), then

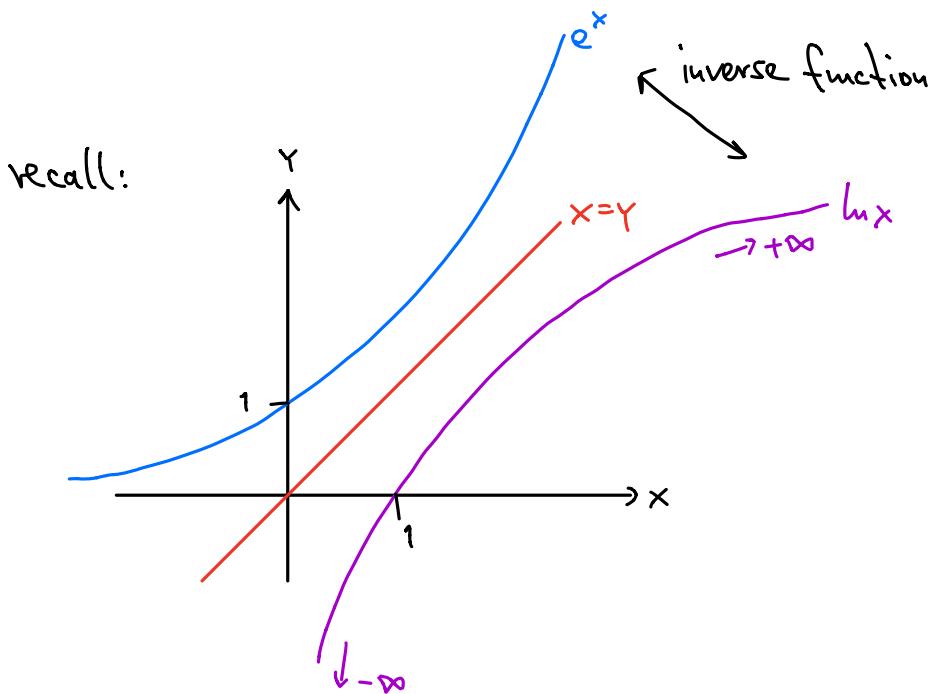
$\int_a^b f(x) dx := \lim_{\substack{\varepsilon \rightarrow 0^+ \\ \text{under}}} \int_{a+\varepsilon}^b f(x) dx$, if it exists, is also called improper integral.
 $= \lim_{\substack{\varepsilon \rightarrow 0 \\ \text{with } \varepsilon > 0}} \int_{a+\varepsilon}^b f(x) dx$

Ex.: for $\alpha > 0, \alpha \neq 1$, consider $f(x) = x^{-\alpha} \Rightarrow$ singular at $x=0$

$$\int_0^1 x^{-\alpha} dx = \lim_{\varepsilon \rightarrow 0^+} \int_\varepsilon^1 x^{-\alpha} dx = \lim_{\varepsilon \rightarrow 0^+} \left. \frac{x^{-\alpha+1}}{-\alpha+1} \right|_\varepsilon^1$$

$$= \lim_{\varepsilon \rightarrow 0^+} \left[\frac{1}{1-\alpha} - \frac{\varepsilon^{1-\alpha}}{1-\alpha} \right] = \begin{cases} \text{divergent if } \alpha > 1 \\ \frac{1}{1-\alpha} \text{ if } 0 < \alpha < 1 \end{cases}$$

note: $\alpha = 1$: $\int_0^1 x^{-1} dx = \lim_{\varepsilon \rightarrow 0^+} |\ln x| \Big|_\varepsilon^1 = \lim_{\varepsilon \rightarrow 0^+} (\underbrace{\ln 1}_{=0} - \ln \varepsilon) \text{ diverges!}$



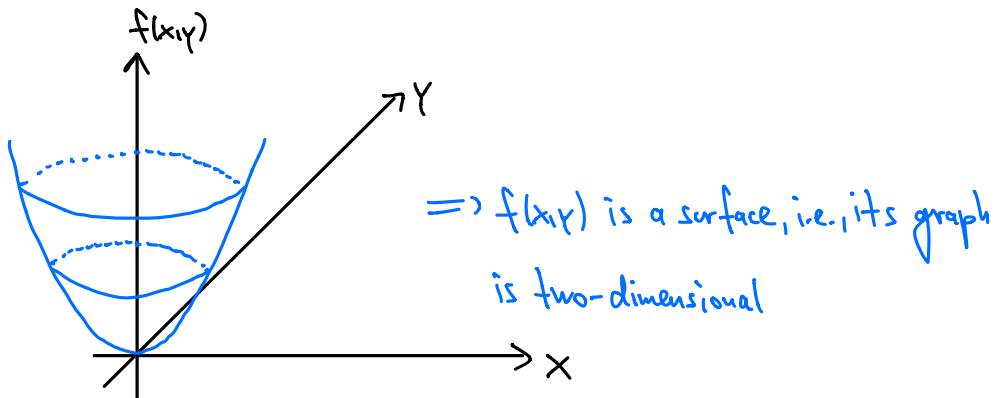
2. Multivariable Calculus: Derivatives

2.1 Partial Derivatives

recall: one-variable function: $f: \mathbb{R} \rightarrow \mathbb{R}, x \mapsto f(x)$

now: $f: \mathbb{R}^2 \rightarrow \mathbb{R}, (x, y) \mapsto f(x, y)$

Ex.: $f(x, y) = x^2 + y^2$



note: $f(x, y, z)$ would be harder to visualize

In general, we consider $f: \mathbb{R}^n \rightarrow \mathbb{R}, (x_1, \dots, x_n) \mapsto f(x_1, \dots, x_n)$, called a

real-valued function on \mathbb{R}^n .

How do we take derivatives, e.g., of $f(x, y) = x^2 + y^2$

↪ keep y fixed, take derivative in x : $\frac{\partial f(x, y)}{\partial x} = 2x$

\Rightarrow usual derivative along x -axis

↪ keep x fixed, take derivative in y : $\frac{\partial f(x, y)}{\partial y} = 2y$

\Rightarrow usual derivative along y -axis

Definition: For $f: \mathbb{R}^n \rightarrow \mathbb{R}$, we call

$$\frac{\partial f(x_1, \dots, x_n)}{\partial x_i} := \lim_{\Delta x_i \rightarrow 0} \frac{f(x_1, \dots, x_i + \Delta x_i, \dots, x_n) - f(x_1, \dots, x_i, \dots, x_n)}{\Delta x_i},$$

if it exists, the i -th partial derivative of f .

Ex.: $f(x_1, x_2, x_3) = \sin(x_1) \cdot x_2^2 + e^{x_3}$

$$\Rightarrow \frac{\partial f}{\partial x_1} = \cos(x_1) x_2^2$$

$$\frac{\partial f}{\partial x_2} = \sin(x_1) 2x_2$$

$$\frac{\partial f}{\partial x_3} = e^{x_3}$$

Note: we can also take higher-order partial derivatives:

e.g., for $f(x, y)$, we can do $\frac{\partial}{\partial x} \left(\frac{\partial f}{\partial x} \right) := \frac{\partial^2 f}{\partial x^2}$,

but also $\frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y} \right) := \frac{\partial^2 f}{\partial x \partial y}$ ("mixed partial derivative"),

or $\frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right) := \frac{\partial^2 f}{\partial y \partial x}$

Ex.: $f(x, y) = \sin(x) \cdot y^3 + x^2$

$$\Rightarrow \frac{\partial f}{\partial x} = \cos(x) y^3 + 2x, \quad \frac{\partial f}{\partial y} = \sin(x) 3y^2$$

$$\frac{\partial^2 f}{\partial x^2} = -\sin(x) y^3 + 2, \quad \frac{\partial^2 f}{\partial y^2} = \sin(x) 6y, \quad \frac{\partial^2 f}{\partial x \partial y} = \cos(x) 3y^2, \quad \frac{\partial^2 f}{\partial y \partial x} = \cos(x) 3y^2$$

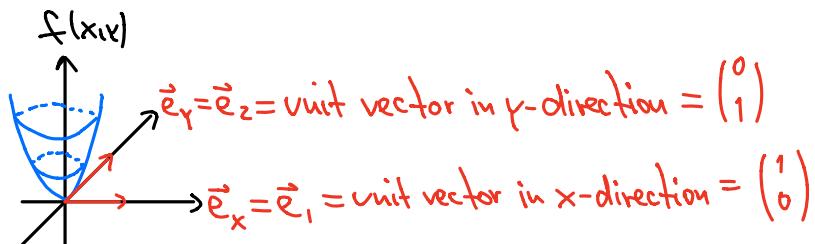
equal!

One can show (no proof here):

Theorem (Clairaut, Schwarz):

If $\frac{\partial^2 f}{\partial x_i \partial x_j}$ and $\frac{\partial^2 f}{\partial x_j \partial x_i}$ are continuous at some point, then $\frac{\partial^2 f}{\partial x_i \partial x_j} = \frac{\partial^2 f}{\partial x_j \partial x_i}$ at that point.

Next: recall



Let us write (x, y) as a vector: $\vec{x} = \begin{pmatrix} x \\ y \end{pmatrix}$, then $f(x, y) = f(\vec{x})$

$$\begin{aligned} \text{def. of partial derivative: } \frac{\partial f}{\partial x} &= \lim_{\Delta x \rightarrow 0} \frac{f(x + \Delta x, y) - f(x, y)}{\Delta x} \\ &= \lim_{\varepsilon \rightarrow 0} \frac{f(\vec{x} + \varepsilon \vec{e}_x) - f(\vec{x})}{\varepsilon} \end{aligned}$$

In this way, we def. the derivative in any direction $\vec{h} = h_1 \vec{e}_1 + \dots + h_n \vec{e}_n = \begin{pmatrix} h_1 \\ \vdots \\ h_n \end{pmatrix}$

Definition (directional derivative):

For any $\vec{h} \in \mathbb{R}^n$, we call

$$D_{\vec{h}} f := \lim_{\varepsilon \rightarrow 0} \frac{f(\vec{x} + \varepsilon \vec{h}) - f(\vec{x})}{\varepsilon} \text{ if it exists, the derivative in direction } \vec{h}.$$

We will see soon how to compute this easily.

Example starting from definition:

How does $f(x,y) = x^2y + 5x$ change in direction $\vec{h} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$?

$$\begin{aligned} \Rightarrow D_h f &= \lim_{\varepsilon \rightarrow 0} \frac{f(\vec{x} + \varepsilon \vec{h}) - f(\vec{x})}{\varepsilon} \quad (\vec{x} + \varepsilon \vec{h} = \vec{x} + \begin{pmatrix} \varepsilon \\ \varepsilon \end{pmatrix} = \begin{pmatrix} x+\varepsilon \\ y+\varepsilon \end{pmatrix}) \\ &= \lim_{\varepsilon \rightarrow 0} \frac{f(x+\varepsilon, y+\varepsilon) - f(x,y)}{\varepsilon} \\ &= \lim_{\varepsilon \rightarrow 0} \frac{(x+\varepsilon)^2(y+\varepsilon) + 5(x+\varepsilon) - [x^2y + 5x]}{\varepsilon} \\ &= \frac{(x^2 + 2x\varepsilon + \varepsilon^2)(y+\varepsilon) + 5\varepsilon - x^2y}{\varepsilon} \\ &= x^2 + 2x\cancel{y} + \underbrace{2x\varepsilon + \varepsilon y + \varepsilon^2}_{\varepsilon \rightarrow 0 \rightarrow 0} + 5 \end{aligned}$$
$$\Rightarrow D_h f = x^2 + 2xy + 5$$