

2.4 The Dual LP Problem

Let us consider another example:

A factory produces cars (x_1) and trucks (x_2). We aim at maximizing the profit $\bar{z} = 3x_1 + 2x_2$, subject to the constraints

$$\text{profit per car} \quad \text{profit per truck} \quad \rightarrow \text{minimize } \bar{z}' = -3x_1 - 2x_2$$

$$5x_1 \leq 100 \quad (\text{car assembly; need 5 h per car; 100 h available}) \quad (1)$$

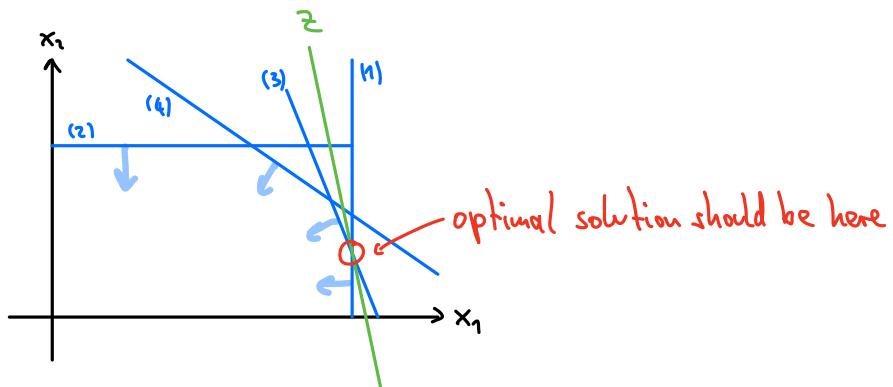
$$10x_2 \leq 100 \quad (\text{truck assembly}) \quad (2)$$

$$4x_1 + 3x_2 \leq 100 \quad (\text{metal stamping}) \quad (3)$$

$$3x_1 + 5x_2 \leq 100 \quad (\text{engine assembly}) \quad (4)$$

$$x_1, x_2 \geq 0$$

Graphically (rough sketch):



Now we would compute the solution via the simplex method:

x_1	x_2	s_1	s_2	s_3	s_4	
5	0	1	0	0	0	100
0	10	0	1	0	0	100
4	3	0	0	1	0	100
3	5	0	0	0	1	100
<hr/>						0
-3	-2	0	0	0	0	0

entry variable: x_1
leaving variable: s_1

	x_1	x_2	s_1	s_2	s_3	s_4	
$R_1/5 \rightarrow R_1:$	1	0	$\frac{1}{5}$	0	0	0	20
$-\frac{4}{5}R_1 + R_2 \rightarrow R_2:$	0	10	0	1	0	0	100
$-\frac{3}{5}R_1 + R_4 \rightarrow R_4:$	0	5	$-\frac{3}{5}$	0	0	1	40
$\frac{3}{5}R_1 + R_5 \rightarrow R_5:$	0	-2	$\frac{3}{5}$	0	0	0	60

entry variable: x_2
leaving variable: s_3

	x_1	x_2	s_1	s_2	s_3	s_4	
$-\frac{10}{3}R_2 + R_1 \rightarrow R_2:$	1	0	$\frac{1}{5}$	0	0	0	20
$R_3/3 \rightarrow R_3:$	0	1	$-\frac{4}{15}$	1	$-\frac{10}{3}$	0	$\frac{100}{3}$
$-\frac{5}{3}R_3 + R_4 \rightarrow R_4:$	0	0	$\frac{11}{15}$	0	$\frac{1}{3}$	1	$\frac{20}{3}$
$\frac{2}{3}R_3 + R_5 \rightarrow R_5:$	0	0	$\frac{1}{15}$	0	$\frac{2}{3}$	0	$\frac{220}{3}$

Done!

\Rightarrow Optimal solution: $x_1 = 20, x_2 = \frac{20}{3}, s_2 = \frac{100}{3}, s_4 = \frac{20}{3}, s_1 = 0, s_3 = 0$, with $\bar{z}' = -\frac{220}{3}$
 (meaning profit $\bar{z} = -\bar{z}' = \frac{220}{3}$)

Now note:

- Constraints 1 and 3 hold with equality (no slack: $s_1=0, s_3=0$). These are the binding constraints.
- Constraints 2 and 4 are non-binding.

Generally:

- We have n physical variables, m slack variables (constraints) here: $n=2, m=4$.
- Unless there is redundancy, m variables are basic.
- Typically, all physical variables are basic, so also $m-n$ slack variables are basic.
- Thus, n slack variables are typically non-basic: These correspond to the binding constraints.

Knowing our optimal solution, we could forget about the non-binding constraints, i.e., we can write our solution in the following way:

$$\text{Let } \hat{A} = \begin{pmatrix} 5 & 0 \\ 4 & 3 \end{pmatrix} \quad \begin{matrix} \xrightarrow{x_1 \ x_2} \\ \leftarrow \text{constraint (1)} \\ \leftarrow \text{constraint (3)} \end{matrix} \quad \hat{b} = \begin{pmatrix} 100 \\ 100 \end{pmatrix}, \text{ want } \hat{A}x = \hat{b}. \quad \begin{matrix} (1) \text{ and (3) are the} \\ \text{binding constraints} \end{matrix}$$

Since \hat{A} is now a square ($n \times n$) matrix with full rank, it can be inverted: $x = \hat{A}^{-1} \hat{b}$.

$$\Rightarrow z' = c^T x = \underbrace{c^T \hat{A}^{-1}}_{=:\tilde{\gamma}^T} \hat{b} = \tilde{\gamma}^T b, \text{ where } \tilde{\gamma} \in \mathbb{R}^2, \gamma \in \mathbb{R}^4 \text{ filled up with zeros.}$$

i.e., here $\tilde{\gamma} = \begin{pmatrix} \dots \\ 0 \\ \dots \\ 0 \end{pmatrix}$

Note: For 2×2 matrices, the formula for the inverse is: $\begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} = \frac{1}{ad-bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$.

$$\text{Here concretely: } \tilde{\gamma}^T = c^T \hat{A}^{-1} = (-3, -2) \begin{pmatrix} 5 & 0 \\ 4 & 3 \end{pmatrix}^{-1} = (-3, -2) \frac{1}{15} \begin{pmatrix} 3 & 0 \\ -4 & 5 \end{pmatrix}$$

$$= \frac{1}{15} (-1, -10). \quad (\Rightarrow \gamma^T = \frac{1}{15} (-1, 0, -10, 0))$$

$$\text{Test: } \tilde{\gamma}^T \hat{b} = \frac{1}{15} (-1, -10) \begin{pmatrix} 100 \\ 100 \end{pmatrix} = \frac{-1100}{15} = -\frac{220}{3} (=z')$$

Now: Change capacities b by a small amount δ (small meaning the binding constraints remain the same).

Then $b \rightarrow b + \delta$ and we need to solve $x = \hat{A}^{-1}(\hat{b} + \tilde{\delta})$.

$$\Rightarrow \text{new profit } z(\delta) = \gamma^T(b + \delta) = \underbrace{\gamma^T b}_{=z(0)} + \gamma^T \delta$$

The $\gamma_1, \dots, \gamma_m$ are called shadow prices. These are the changes of profit per unit of capacity at current operating conditions.

Indeed, the following holds:

Theorem: The value of a company in terms of maximal profit from its operation equals the value of all its resources valued at the current shadow prices.

Proof: Set $\delta = -b$, so $\bar{z}(\delta) = \gamma^T(b - b) = 0$ (no resources, no operations, no profit)

↳ Note: this does not change the binding constraints (even though $\delta = -b$ is large), since we just rescale the feasible region proportionally.

Thus $\bar{z}(\delta) = \bar{z}(0) - \gamma^T b = 0$, so $\underbrace{\bar{z}(0)}_{\substack{\text{value of the} \\ \text{Company}}} = \underbrace{\gamma^T b}_{\substack{\text{resources valued} \\ \text{at shadow prices}}}$.

□