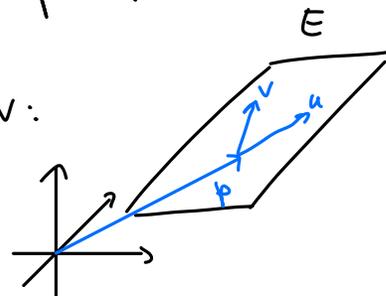


### 3.5 Surface Integrals

First, a short review of planes, normal vectors, and the cross product.

A plane  $E$  can be parametrized by specifying vectors  $p, u, v$ :

$$E = \{x \in \mathbb{R}^3 : x = p + su + tv, s, t \in \mathbb{R}\}$$



This can be written as

$$\underbrace{\begin{pmatrix} | & | & | \\ p-x & u & v \\ | & | & | \end{pmatrix}}_{=A} \begin{pmatrix} 1 \\ s \\ t \end{pmatrix} = 0$$

column vectors

with  $A$  singular, i.e.,  $\det A = 0$ .  
 $\Leftrightarrow Ax = 0$  has a solution  $x \neq 0$

Now recall the Laplace expansion from linear Algebra:

$$\det \begin{pmatrix} (p-x)_1 & u_1 & v_1 \\ (p-x)_2 & u_2 & v_2 \\ (p-x)_3 & u_3 & v_3 \end{pmatrix} = (p-x)_1 \underbrace{\det \begin{pmatrix} u_2 & v_2 \\ u_3 & v_3 \end{pmatrix}}_{=u_2v_3 - u_3v_2 =: n_1} + (p-x)_2 \underbrace{(-1) \det \begin{pmatrix} u_1 & v_1 \\ u_3 & v_3 \end{pmatrix}}_{=u_3v_1 - u_1v_3 =: n_2} + (p-x)_3 \underbrace{\det \begin{pmatrix} u_1 & v_1 \\ u_2 & v_2 \end{pmatrix}}_{=u_1v_2 - u_2v_1 =: n_3}$$

$$=: (p-x) \cdot n$$

Thus,  $n = u \times v$  (cross product), and the eq. of a plane can be written as

$$(p-x) \cdot (u \times v) = 0.$$

Note/recall the properties of the cross product:

- $u \times v = -v \times u$
- $\det \begin{pmatrix} | & | & | \\ a & b & c \\ | & | & | \end{pmatrix} = a \cdot (b \times c)$
- $u \times v$  is perpendicular to  $u$  and  $v$

- $u \times v = 0$  if  $u$  and  $v$  are linearly dependent

- The area of a parallelogram spanned by  $u$  and  $v$  is  $\|u \times v\| = \|u\| \|v\| \sin \theta$ ,

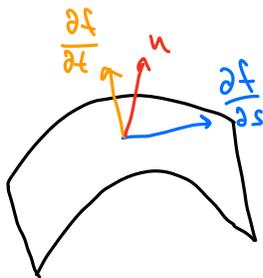
with  $\theta = \text{angle between } u, v$

- $\|u \times v\|^2 = \|u\|^2 \|v\|^2 - (u \cdot v)^2$

Next: More generally, a surface  $M \subset \mathbb{R}^3$  can be parametrized by a fct.  $f(s, t)$ , with  $f \in C(\bar{U}, \mathbb{R}^3)$ ,  $U \subset \mathbb{R}^2$  a domain. Then  $M = \text{range of } f$ .

$:= \{y \in \mathbb{R}^3 : f(s, t) = y \text{ for some } (s, t) \in \bar{U}\}$ .

We call  $M$  smooth if  $f \in C^1(U, \mathbb{R}^3)$  and  $n := \frac{\partial f}{\partial s} \times \frac{\partial f}{\partial t} \neq 0$  on  $U$ .



$\rightarrow \frac{\partial f}{\partial s}, \frac{\partial f}{\partial t}$  are tangent vectors (spanning the tangent plane)

$\rightarrow n$  is a normal vector (perpendicular to tangent plane)

We define the unit normal vector  $\hat{n} = \frac{n}{\|n\|}$ .

Analogous to line integrals, we define:

- the surface area  $\sigma(M) := \int_U \|n\| dS$ ,  $\leftarrow \text{analogous to } A(|f|) = \int_a^b \|f'(t)\| dt$

"Integrating up infinitesimal surface elements"

- for  $\phi \in C(M, \mathbb{R})$  the surface integral  $\int_M \phi d\sigma := \int_U \phi \circ f \|n\| dS$ ,  $\leftarrow \text{analogous to } \int_a^b \phi(f(t)) \|f'(t)\| dt$

- for  $F \in C(M, \mathbb{R}^3)$  the flux integral  $\int_M F \cdot \hat{n} d\sigma := \int_U (F \circ f) \cdot n dS$ ,  $\leftarrow \text{analogous to } \int_a^b (F \circ f)(t) \cdot f'(t) dt$

$\downarrow$   
normalized normal vector

Examples:

• Surface area of a sphere: We can choose  $f(\theta, \varphi) = \begin{pmatrix} \sin\theta \cos\varphi \\ \sin\theta \sin\varphi \\ \cos\theta \end{pmatrix}$ ,  $\varphi \in [0, 2\pi]$ ,  $\theta \in [0, \pi]$ .

(as for spherical coordinates)

$$\text{Then: } \frac{\partial f}{\partial \theta} = \begin{pmatrix} \cos\theta \cos\varphi \\ \cos\theta \sin\varphi \\ -\sin\theta \end{pmatrix}, \quad \frac{\partial f}{\partial \varphi} = \begin{pmatrix} -\sin\theta \sin\varphi \\ \sin\theta \cos\varphi \\ 0 \end{pmatrix}$$

$$\Rightarrow n = \frac{\partial f}{\partial \theta} \times \frac{\partial f}{\partial \varphi} = \begin{pmatrix} 0 + \sin^2\theta \cos\varphi \\ \sin^2\theta \sin\varphi - 0 \\ \cos\theta \sin\theta (\cos^2\varphi + \sin^2\varphi) \end{pmatrix} = \begin{pmatrix} \sin^2\theta \cos\varphi \\ \sin^2\theta \sin\varphi \\ \cos\theta \sin\theta \end{pmatrix}$$

$$\Rightarrow \|n\|^2 = \underbrace{\sin^4\theta \cos^2\varphi + \sin^4\theta \sin^2\varphi}_{=\sin^4\theta} + \cos^2\theta \sin^2\theta = \sin^2\theta (\sin^2\theta + \cos^2\theta) = \sin^2\theta$$

$$\Rightarrow \|n\| = \sin\theta$$

$$\Rightarrow \sigma(\text{sphere}) = \int_0^{2\pi} \int_0^\pi \sin\theta \, d\theta \, d\varphi = 2\pi (-\cos\theta) \Big|_0^\pi = 4\pi.$$

•  $M$  = upper hemisphere of radius 1 centered at  $O$ ,  $\phi(x, y, z) = (x^2 + y^2)z$ .

We use the same  $f$  as above with  $\varphi \in [0, 2\pi]$  but  $\theta \in [0, \frac{\pi}{2}]$  only.

$$\begin{aligned} \Rightarrow \int_M \phi \, d\sigma &= \int_0^{2\pi} \int_0^{\frac{\pi}{2}} \phi(f(\theta, \varphi)) \|n(\theta, \varphi)\| \, d\theta \, d\varphi \\ &= \int_0^{2\pi} \int_0^{\frac{\pi}{2}} \sin^2\theta (\cos^2\varphi + \sin^2\varphi) \cos\theta \underbrace{\sin\theta}_{=\|n\|} \, d\theta \, d\varphi \\ &= \int_0^{2\pi} \int_0^{\frac{\pi}{2}} \sin^3\theta \cos\theta \, d\theta \, d\varphi \\ &= 2\pi \left. \frac{1}{4} \sin^4\theta \right|_0^{\frac{\pi}{2}} \\ &= \frac{\pi}{2}. \end{aligned}$$

• Same  $M$ ,  $F = \frac{1}{x^2+y^2+z^2} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \Rightarrow F(f(\theta, \varphi)) = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$   
since  $(\sin\theta\cos\varphi)^2 + (\sin\theta\sin\varphi)^2 + (\cos\theta)^2 = 1$ .

$$\Rightarrow \int_M F \cdot \hat{n} \, d\sigma = \int_0^{2\pi} \int_0^{\frac{\pi}{2}} \underbrace{F(f(\theta, \varphi))}_{= \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}} \cdot \underbrace{n(\theta, \varphi)}_{= \begin{pmatrix} \sin^2\theta \cos\varphi \\ \sin^2\theta \sin\varphi \\ \cos\theta \sin\theta \end{pmatrix}} d\theta d\varphi$$

outward pointing  $\swarrow$

$$= \int_0^{2\pi} \int_0^{\frac{\pi}{2}} (\sin^2\theta \cos\varphi + \sin^2\theta \sin\varphi + \cos\theta \sin\theta) d\theta d\varphi$$

$$= \int_0^{\frac{\pi}{2}} \sin^2\theta d\theta \underbrace{\int_0^{2\pi} (\cos\varphi + \sin\varphi) d\varphi}_{=0} + 2\pi \frac{1}{2} \sin^2\theta \Big|_0^{\frac{\pi}{2}}$$

$$= \pi$$